



# Introduction

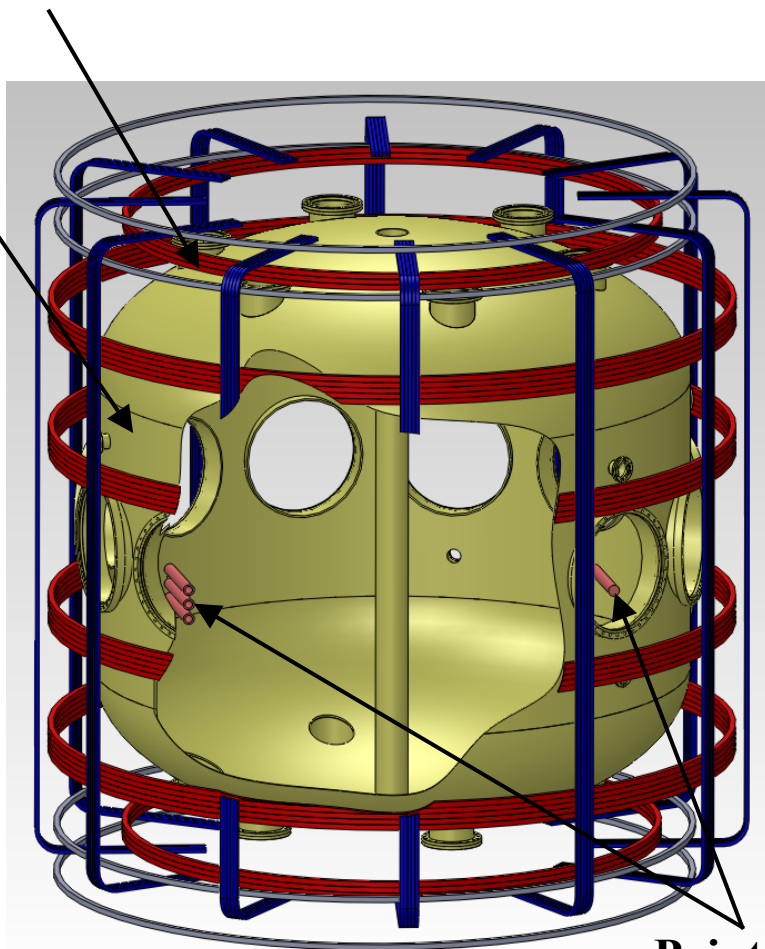
- Helicity injection research on Pegasus motivates a set of facility upgrades
  - Improved toroidal field strength and injector bias system can increase plasma current from helicity injection
  - Increased position and shaping control can improve coupling of plasma to helicity injectors
  - Increasing complexity of power supply systems demands improved feedback control and fault handling



# PEGASUS: A University Scale, Ultralow-A ST

## Equilibrium Field Coils

Vacuum Vessel



Point-Source  
Helicity Injectors

## Experimental Parameters

Parameter	Achieved	Goals
A	1.15 – 1.3	1.12 – 1.3
R(m)	0.2 – 0.45	0.2 – 0.45
$I_p$ (MA)	$\leq .21$	$\leq 0.30$
$I_N$ (MA/m-T)	6 – 12	6 – 20
$RB_t$ (T-m)	$\leq 0.06$	$\leq 0.1$
$\kappa$	1.4 – 3.7	1.4 – 3.7
$\tau_{\text{shot}}$ (s)	$\leq 0.025$	$\leq 0.05$
$\beta_t$ (%)	$\leq 25$	$> 40$
$P_{\text{HHFW}}$ (MW)	0.2	1.0

## Major research thrusts include:

- *Non-inductive startup and sustainment*
- *Tokamak physics in small aspect ratio:*
  - *High- $I_N$ , high- $\beta$  stability limits*
  - *ELM-relevant edge MHD activity*



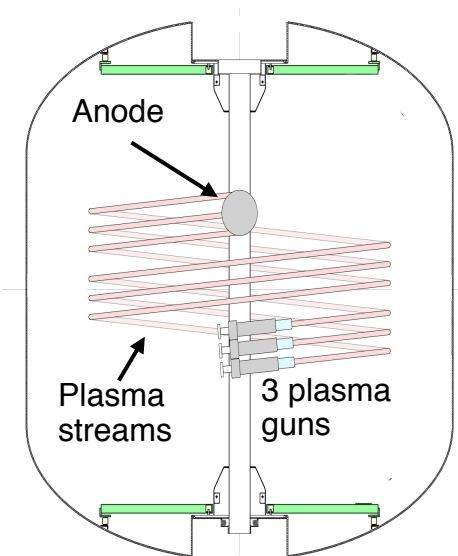


# Helicity Injector Physics Motivates Facility Upgrades

- Taylor Limit – maximum  $I_p$  from HI:
  - Depends on injector current, toroidal field current, injector width
- Helicity injection loop voltage:
  - Proportional to  $B$  normal to injector surface, injector area, injector bias voltage
- Motivates increases in  $I_{inj}$ ,  $I_{TF}$  through facility upgrades
  - Upgraded TF power supplies
  - Upgraded injector bias system
- Ref: D.J. Battaglia, Tokamak Startup Using Outboard Current Injection on the Pegasus Toroidal Experiment  
*Nuclear Fusion* **51**, 073029 (2011)

$$I_{p,max} \propto \sqrt{\frac{I_{inj} \cdot I_{TF}}{w}}$$

$$V_{eff} \propto \frac{B_{inj} \cdot A_{inj} \cdot V_{bias}}{\psi_T}$$





# Compact Plasma Arc Sources Provide Dense Plasma for Electron Current Extraction

- Plasma arc(s) biased relative to anode:

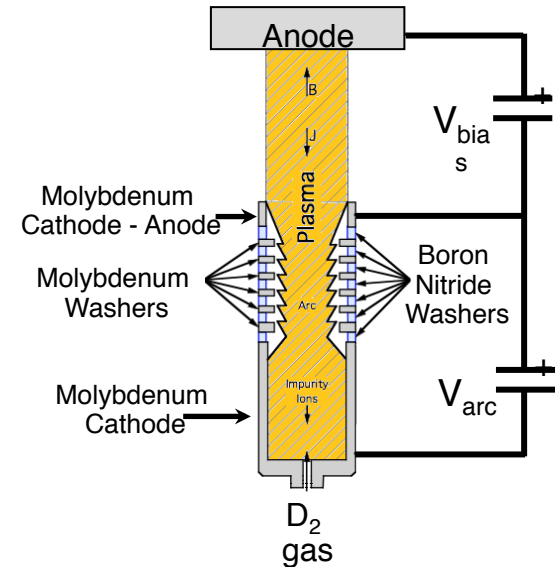
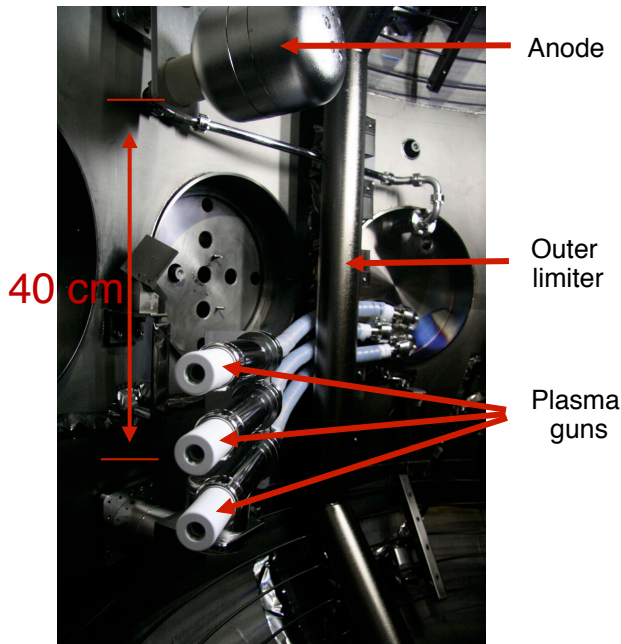
- Helicity injection rate:

$$\dot{K}_{inj} = 2V_{inj}B_N A_{inj}$$

$V_{inj}$  - injector voltage

$B_N$  - normal B field at gun aperture

$A_{inj}$  - injector area



- Arc plasma fully ionized
  - $N_e \sim 10^{20} \text{ m}^{-3}$
  - $T_e \sim 10 \text{ eV}$
  - Dia = 1.6 cm
  - $I_{arc} \sim 2 \text{ kA}$





# Pegasus Employs Modular Switching Power Supplies

- Two banks of switching power supplies on Pegasus

- Bank A: 12 x 2700V IGCT Bridges

- Ohmic
    - New high voltage injector bias

- Bank B: 28 x 900V IGBT Bridges

- Toroidal Field Coils
    - Poloidal Fields Coils
    - Divertor Coils
    - Low voltage injector bias

- Power supplies are modular and reconfigurable

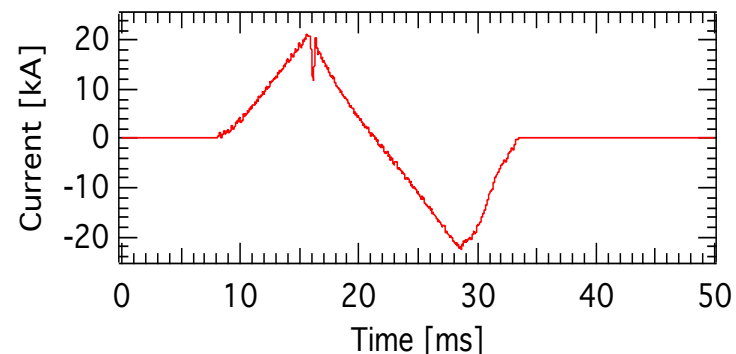
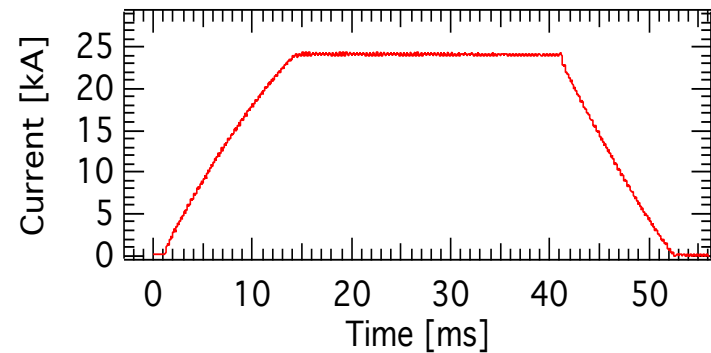
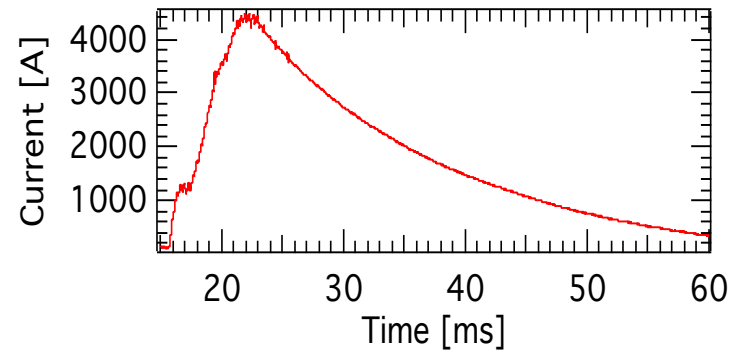
- Allows reassignment of bridges between systems as needed





# Systems Powered by Three Types of Bridges

- **One Quadrant Bridges**
  - Unipolar drive / coast
  - e.g., – injector bias system
- **Two Quadrant Bridges**
  - Unipolar drive / regen
  - e.g., – toroidal field coils
- **Four Quadrant Bridges**
  - Bipolar drive / regen
  - e.g., – ohmic





# New Bridge Technology Enables Doubling of Toroidal Field

- Improved IGBT technology supports TF increase from 0.15T to 0.3T
  - 6 4-kA IGBT bridges replaced by 8 6-kA IGBT bridges
    - 288 kA-turns  $\rightarrow$  576 kA-turns
  - Improved performance enables
    - Switching for twice the duration at same current
    - Switching for same duration at 50% higher current
- Original TF bridges now free for other use
  - PF upgrade / divertor coils



New TF silicon



# Advantages of New IGBT Technology

## Present System:

### Eupec FZ2400R17KE3 IGBT

- Steady state voltage rating: 1200V, 2.4kA
- Pulsed rating: 900V, 2.4kA at 1kHz - Switching Frequency
- Repeated operation at 2x switch rating (4.8kA)
- Voltage switching up to 3kHz, dependent on switch topology, controller
- Heat sink: traditional copper base plate

## Augmented System:

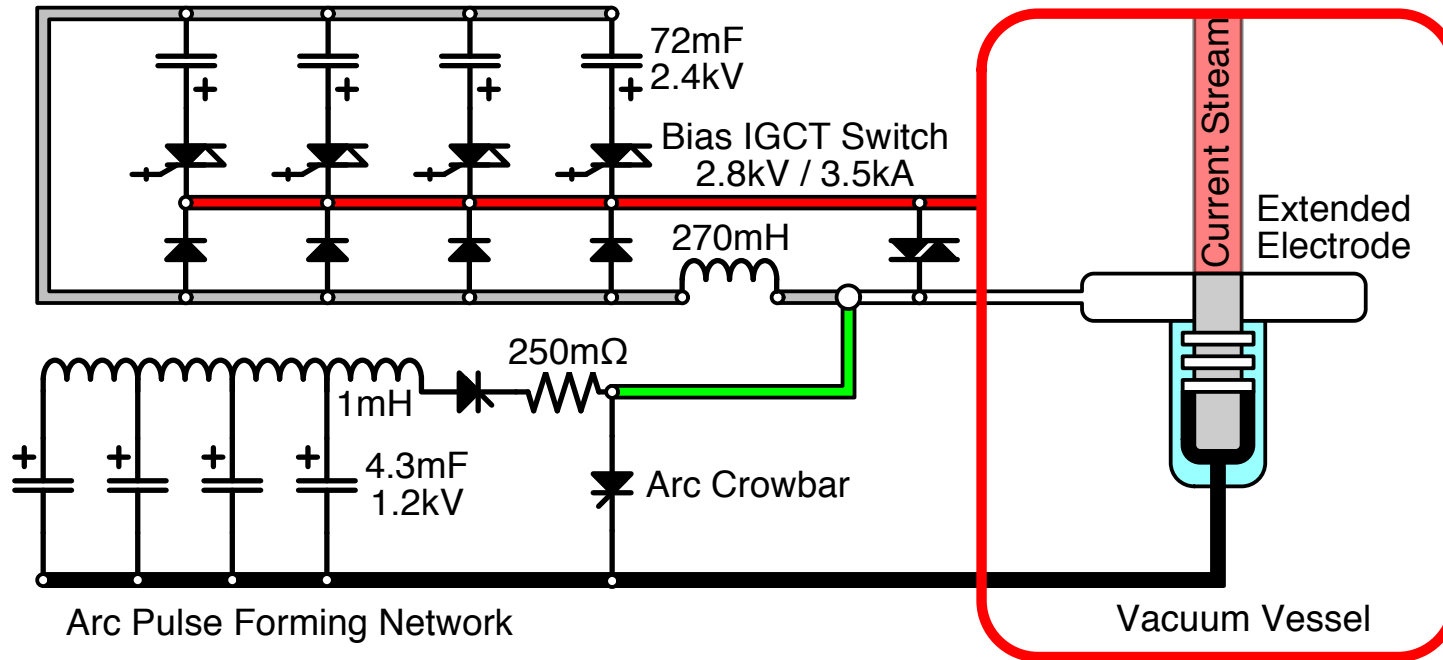
### Eupec FZ3600R17HP4-B2 IGBT

- Steady state voltage rating: 1700V, 3.6kA
- Pulsed rating: 900V, 3.6kA at 1kHz switching frequency
- Repeated operation at 2x switch rating (7.2kA)
- Voltage switching up to 10+ kHz, dependent on controller
- Heat sink: AlSiC base plate for increased thermal cycling capability (better pulsed power performance)





# New IGCT Bias System Increases Injector Current and Voltage

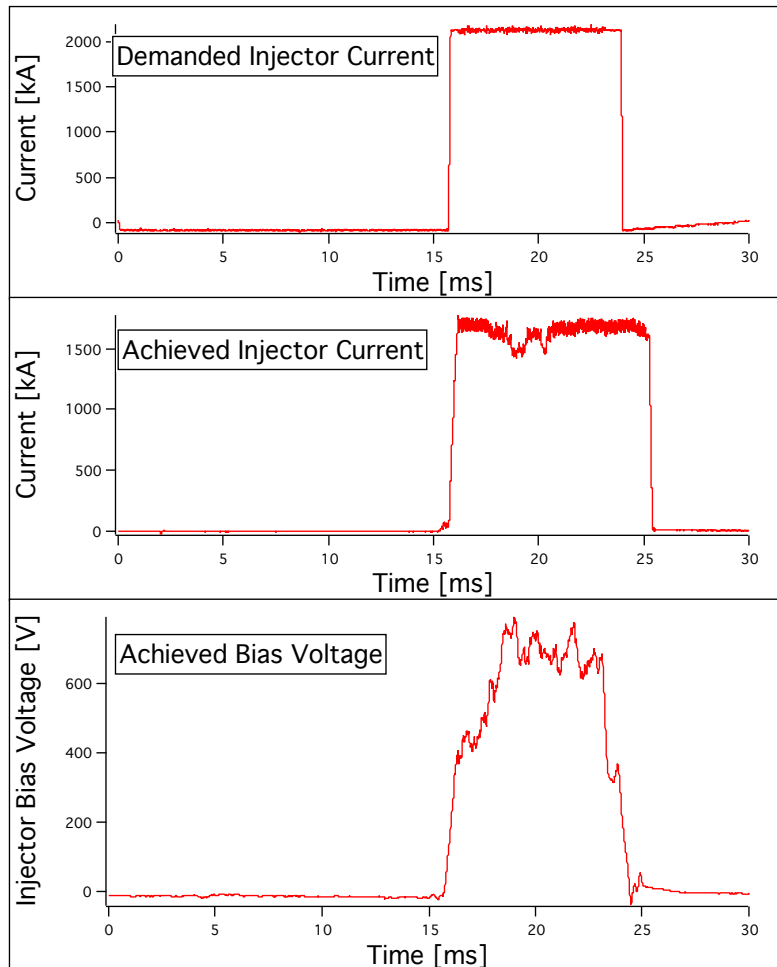


- Four 1-quad IGCT bridges supply up to 14kA injector current at up to 2kV
- Helicity rate  $\sim V_{\text{bias}}$
- Taylor Limit  $\sim \sqrt{I_{\text{inj}}}$

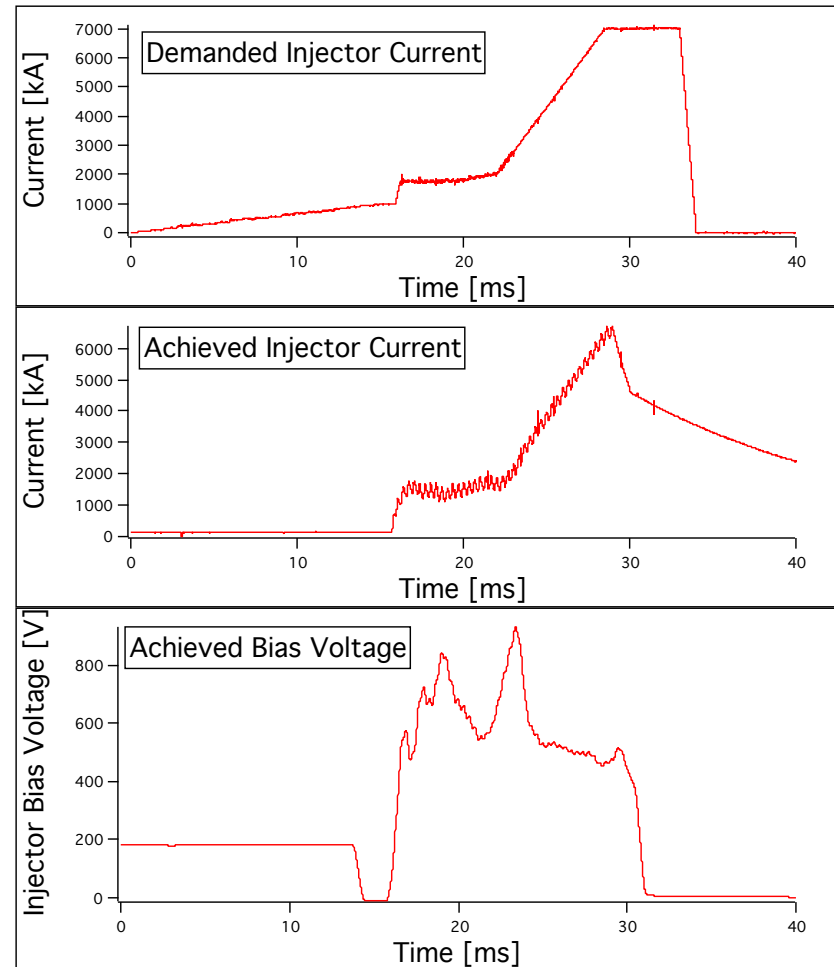


# Increased Injector Current for Helicity Drive

## IGBT Bias System



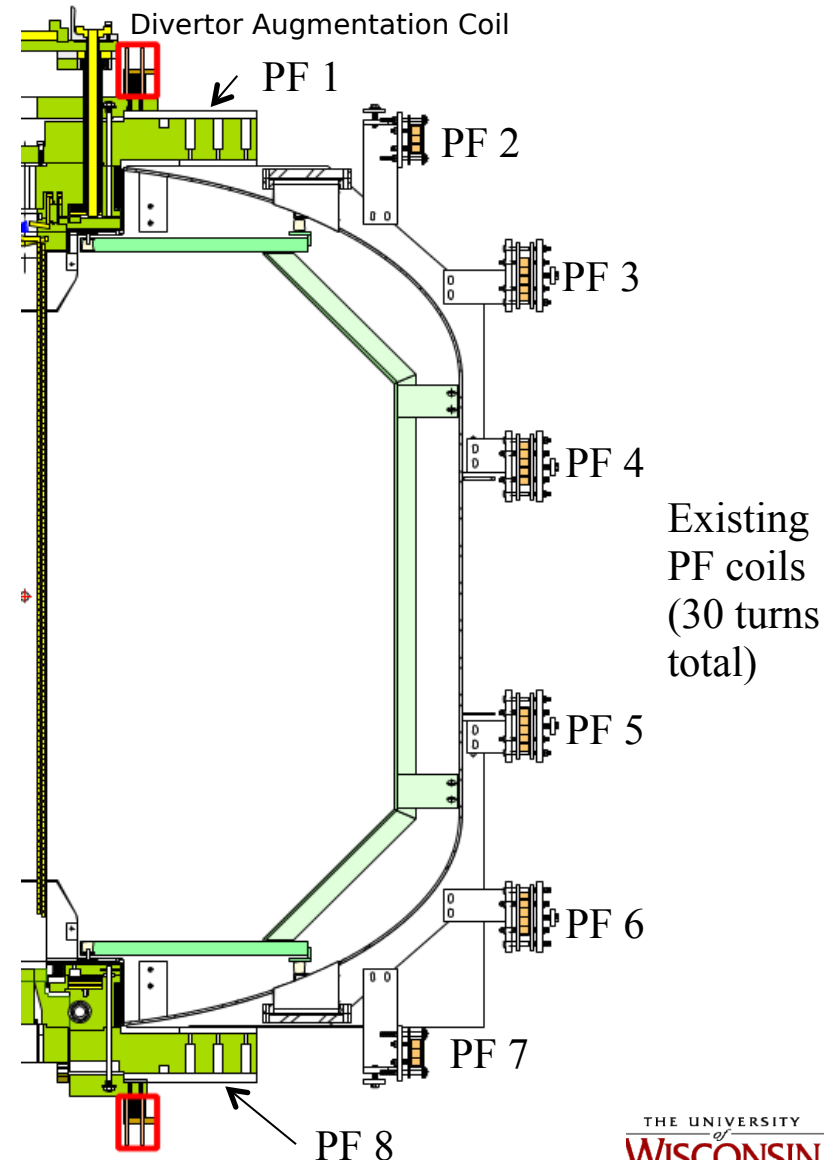
## IGCT Bias System





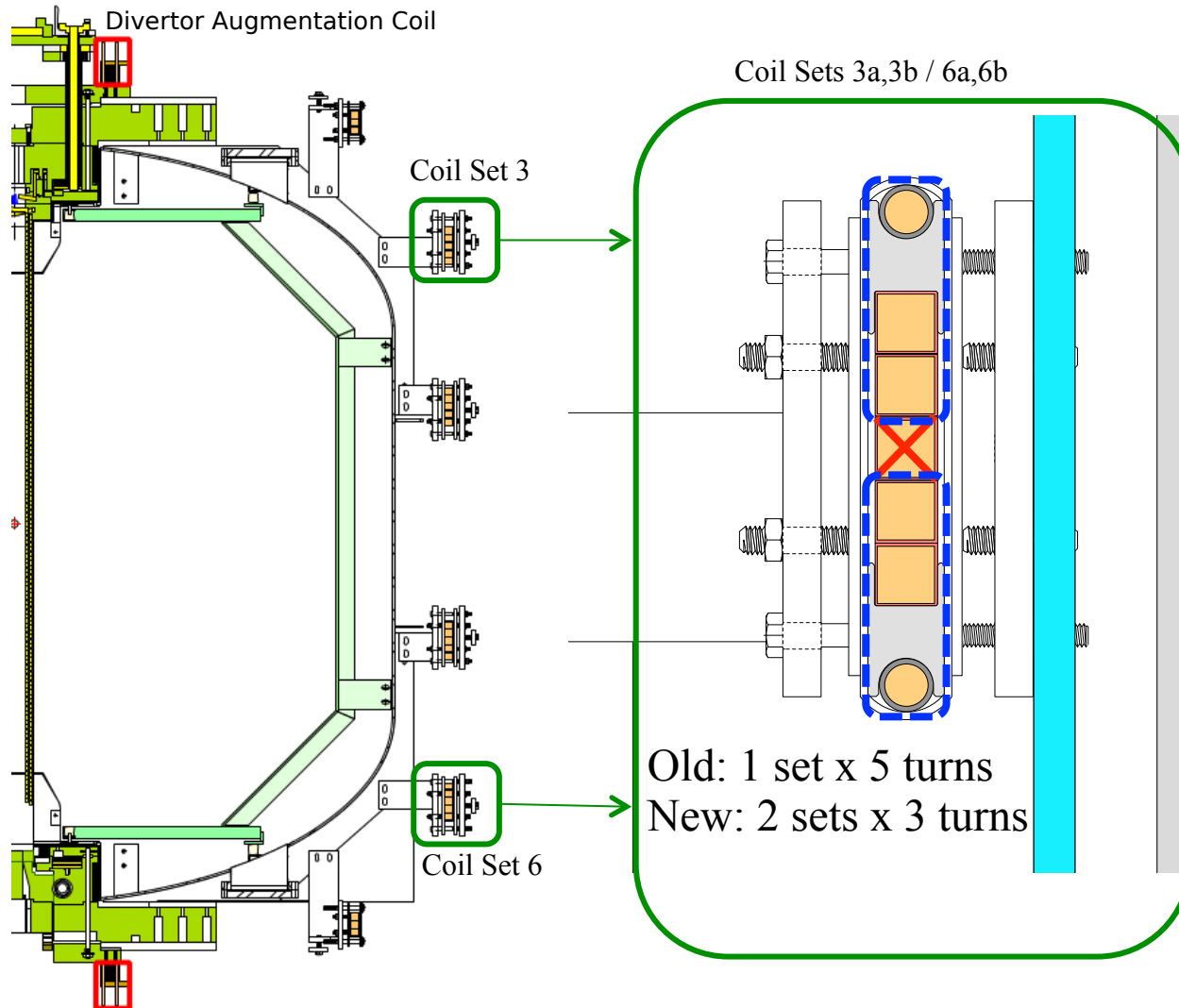
# Planned Expansion of Poloidal Field Coils

- Presently poloidal field is driven by 8 coils sets with a total of 30 turns
- PF time response important for position control, poloidal induction
  - Limited by coil rise time ( $L/R$ ), penetration of vacuum vessel
- Modifications chosen to improve time response:
  - Decrease turns per coil set
  - Increase number of independent coil sets, using former TF power supplies





# More Independently Driven PF Coil Sets



Modifications to coil sets 3 and 6:

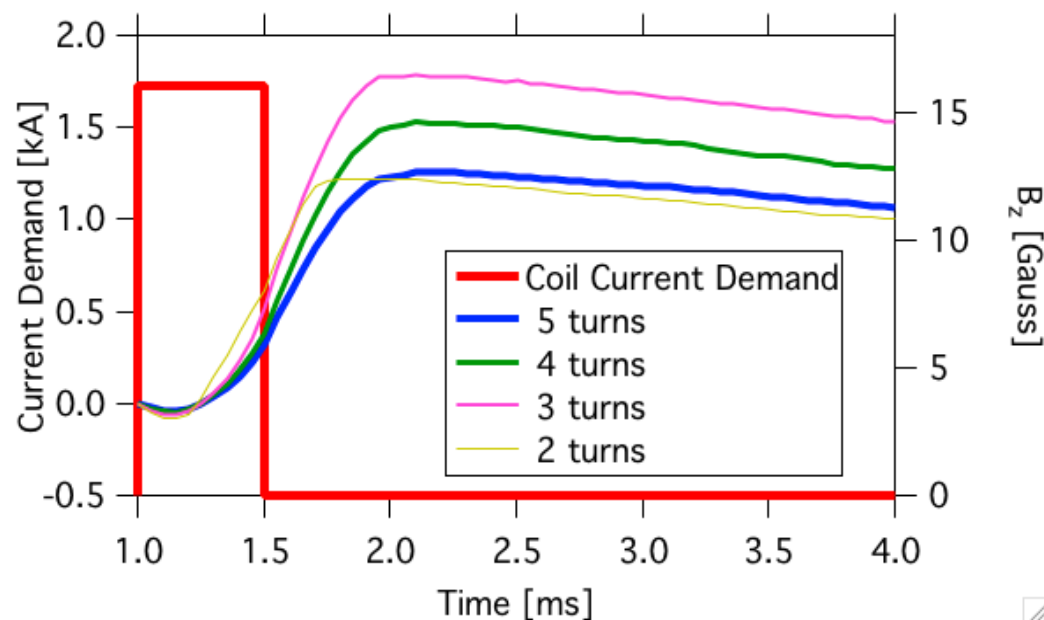
- new turns added above and below
- Each set split into 2 sets of 3 turns





# Number of Turns Drives PF Response Time

- Wall code simulations used to find optimal # turns / coil set in Pegasus
  - Balance of coil rise time vs. wall penetration time
- Response time characterized using 0.5ms square pulse
  - Figure of merit:  $B_z(t)$  at  $R=0.4\text{m}$
- 3 turns/set gives optimal response time for available power supplies

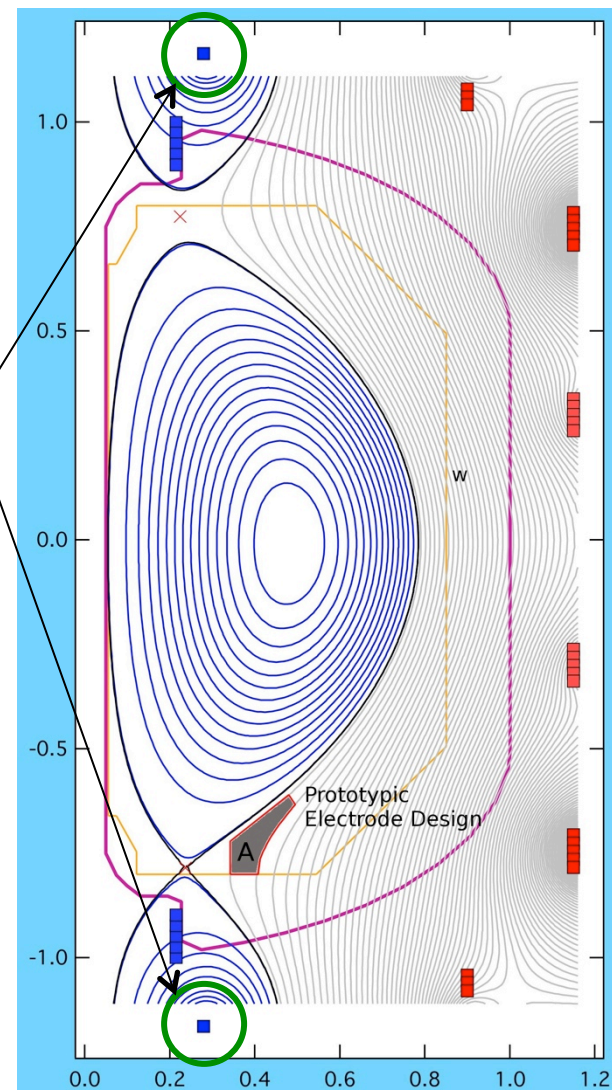




# New Divertor Coils Will Enable Full Separatrix Operation

- New divertor coils designed
  - achieve higher helicity injection rate through flux expansion in divertor region
  - Conduct H-mode studies; path towards high- $\beta$
- 26 turns carrying up to 4kA support single null and double null topology with  $I_p \leq 300\text{kA}$
- Full divertor design presented by P. Shriwise
  - Poster NP8.00067

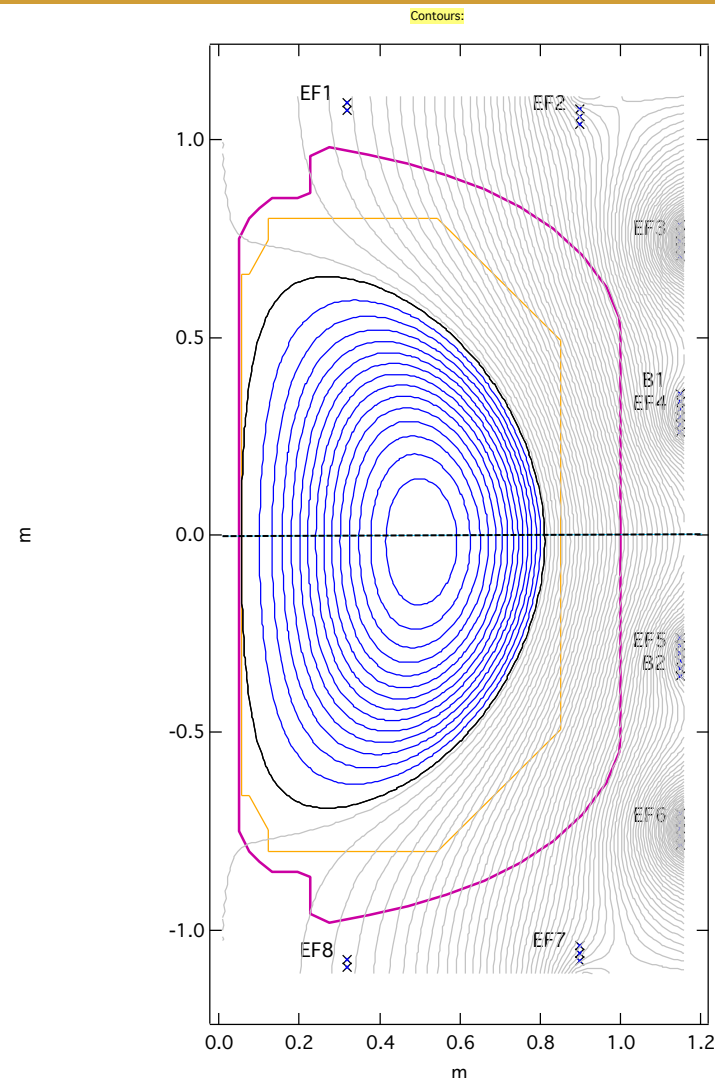
New Divertors





# Exploration of Improved Vertical Position Control

- Plasma vertical position control desirable:
  - Compensates for magnetic field errors
  - Provides control flexibility
    - Optimize current coupling to helicity injector
- Three avenues under consideration:
  - Run top/bottom divertor coils in opposing directions (anti-series)
  - Additional turns to PF coils closest to midplane – running opposed current
  - Run main PF coils up-down assymmetric





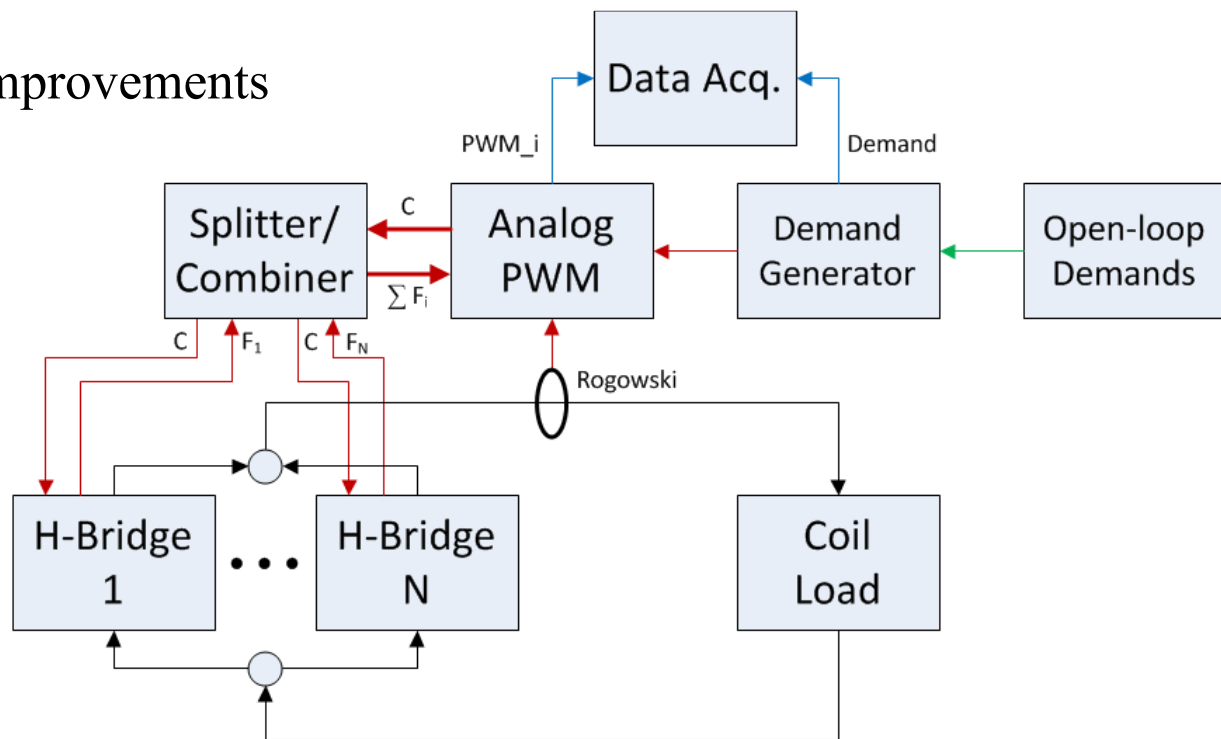
# Control Enhancements Accompany Power Supply Upgrades

- Power supply control system improvements motivated by:
  - Increasing number of bridges require additional control channels
  - Need to handle and log hardware faults
  - Advanced feedback control of magnetic field coils and DC helicity injectors
  - Need for more independent feedback controllers and fault detectors
- Two approaches being pursued to implement these goals
  - Near-term: improvements to existing analog system
  - Medium-term: advanced digital control (FPGA)



# Near Term Control System Modifications

- Stage 1: Improvements to present analog system
  - Improved bridge protection logic
  - Deployed more PWMs
  - CAMAC timing improvements

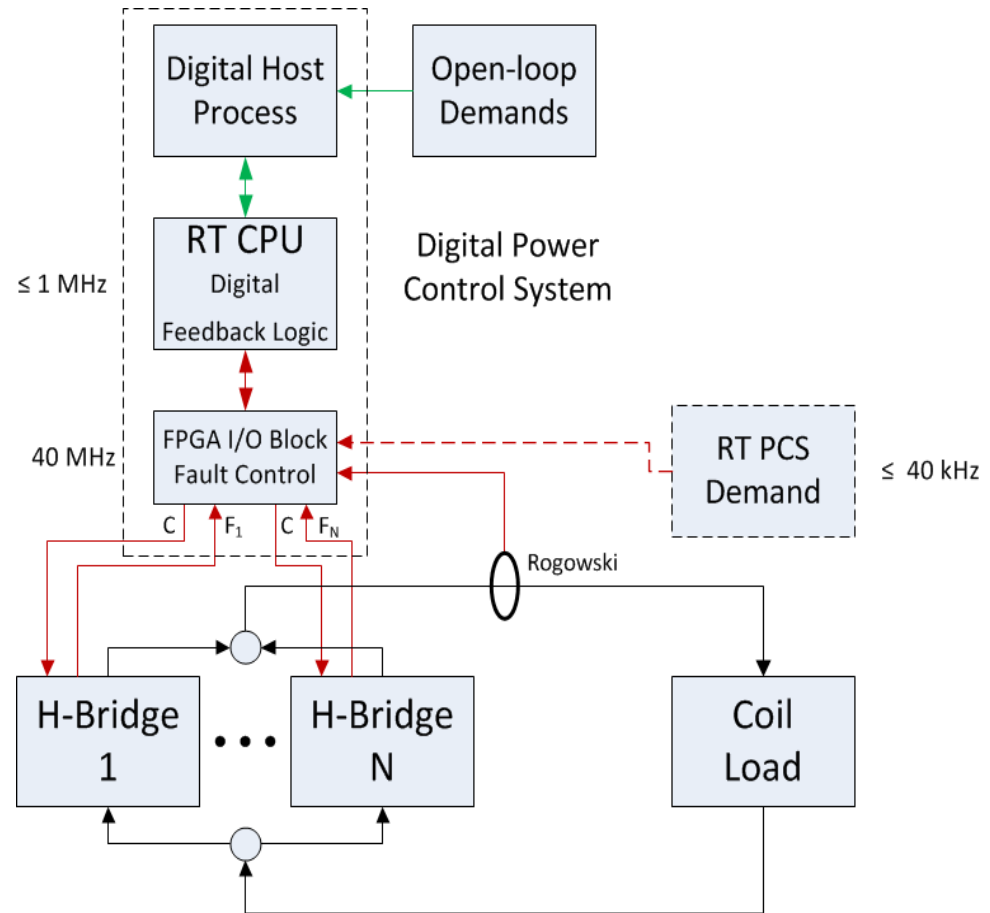




# Digital Feedback Control

## Stage 2: Digital control system

- based on NI FPGA technology
- Enables  $\sim 5\text{MHz}$  digital polling of bridge states
- FPGA level fault handling
- Realtime controller provides  $5\text{kHz}$  feedback control
- Fully replaces analog PWM, splitter/combiner hardware





# Summary

A set of current and planned upgrades will improve the physics capability of Pegasus

- Power supply upgrades boost HI capabilities:
  - Toroidal field kA-turns doubled
  - High voltage, high current injector bias system
- Magnetic field coils enable increased position and shaping control
  - Expanded PF coils for faster time response
  - New divertor coils will allow improved helicity injection, H-mode studies
  - Vertical position control – options under consideration
- Control systems advanced to meet needs of new power systems
  - Near term: improvements to analog control systems
  - Medium term: advanced digital control